

# Summary of Event-B Proof Obligations

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Bucharest DEPLOY 2-day Course, 14th-16th, July, 2010



# Purpose of this Presentation

- **Prerequisite:**
  - 1 Summary of **Mathematical Notation** (a quick review)
  - 2 Summary of **Event-B Notation**Examples developed in (2) will be used here
- Showing the various Event-B **proof obligations** (sometimes also called **verification conditions**)



# Role of the Proof Obligation Generator

- The POs are **automatically** generated by a **Rodin Platform tool** called the **Proof Obligation Generator**
- This tool is run after the **Static Checker** (which **static checks contexts** or **machine texts**)
- The **Proof Obligation Generator** decides then **what is to be proved**
- The **outcome** are various **sequents**, which are transmitted to the **provers** performing **automatic** or **interactive** proofs

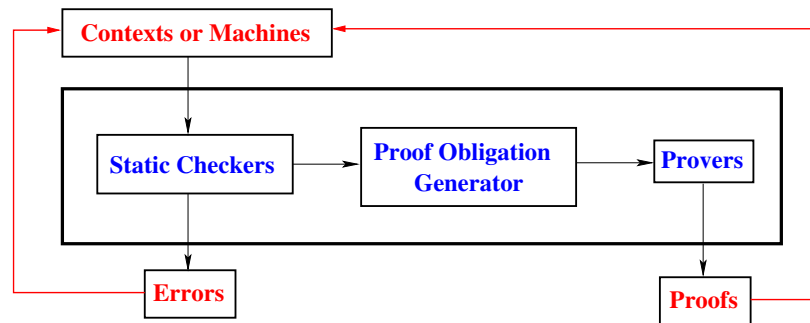


# Summary of the Main Rodin Platform Kernel Tools

- The **Static Checkers:**
  - lexical analyser
  - syntactic analyser
  - type checker
- The **Proof Obligation Generator**
- The **Provers**



## Summary of the Main Rodin Platform Kernel Tools



- Proofs which cannot be done help **improving the model**



## Various Kinds of Proof Obligations

- Invariant preservation (initial model) (**INV** slide 9)
- Non-deterministic action feasibility (**FIS** slide 14)
- Guard strengthening in a refinement (**GRD** slide 18)
- Invariant preservation in a refinement (**INV** slide 22)
- Simulation (**SIM** slide 26)
- Numeric variant (**NAT** slide 30)
- Set variant (**FIN** slide 34)



## Various Kinds of Proof Obligations (cont'd)

- Variant decreasing (**VAR** slide 38)
- Feasibility of a non-deterministic witness (**WFIS** slide 46)
- Proving theorems (**THM** slide 50)
- Well-definedness (**WD** slide 58)
- Guard strengthening when merging abstract events (**MRG** slide 62)



## Outline of each Proof Obligation

- Purpose and naming
- Formal definition
- Where generated in the “search” example
- Application to the example



## Purpose of Invariant Preservation PO (INV) (for Initial Model)

- Ensuring that each **invariant is preserved by each event**.
- For an event “**evt**” and an invariant “**inv**” the name of this PO is:  
evt/inv/INV



## Formal Definition of Invariant Preservation (INV) (for Initial Model)

<pre> evt any x where   G(x, s, c, v) then   v := BAP(x, s, c, v, v') end         </pre>	<p>s : seen sets c : seen constants v : variables A(s, c) : seen axioms I(s, c, v) : invariants evt : specific event x : event parameters G(x, s, c, v) : event guards BAP(x, s, c, v, v') : event before-after predicate i(s, c, v') : modified specific invariant</p>
--	---

<p>Axioms Invariants Guards of the event Before-after predicate of the event ⊢ Modified Specific Invariant</p>	<p>evt/inv/INV</p>	<p>A(s, c) I(s, c, v) G(x, s, c, v) BAP(x, s, c, v, v') ⊢ i(s, c, v')</p>
--	--------------------	---

- In case of the initialization event,  $I(s, c, v)$  is removed from the hypotheses



## Examples in Machine m\_0a (INV)

```

context
  ctx_0
sets
  D
constants
  n
  f
  v
axioms
  axm1 : n ∈ ℕ
  axm2 : f ∈ 1..n → D
  axm3 : v ∈ ran(f)
  thm1 : n ∈ ℕ1
end
        
```

```

initialisation ≡
  status
  ordinary
  then
  act1 : i := 1
  end
        
```

```

search ≡
  status
  ordinary
  any
  k
  where
  grd1 : k ∈ 1..n
  grd2 : f(k) = v
  then
  act1 : i := k
  end
        
```

```

machine
  m_0a
sees
  ctx_0
variables
  i
invariants
  inv1 : i ∈ 1..n
events
  ...
end
        
```

- Two invariant preservation POs are generated:
- initialisation/inv1/INV
  - search/inv1/INV



## Proof Obligation **initialisation/inv1/INV**

```

axm1
axm2
axm3
thm1
BA predicate
⊢
modified inv1
        
```

```

n ∈ ℕ
f ∈ 1..n → D
v ∈ ran(f)
n ∈ ℕ1
i' = 1
⊢
i' ∈ 1..n
        
```

```

n ∈ ℕ
f ∈ 1..n → D
v ∈ ran(f)
n ∈ ℕ1
⊢
1 ∈ 1..n
        
```

Simplification performed  
by the PO Generator

```

initialisation ≡
  status
  ordinary
  then
  act1 : i := 1
  end
        
```

- Note that **inv1** is **not part of the hypotheses** (we are in the **initialisation** event)



# Proof Obligation **search/inv1/INV**

<pre>axm1 axm2 axm3 thm1 inv1 grd1 grd2 BA predicate ⊢ modified inv1</pre>	<pre>n ∈ ℕ f ∈ 1..n → D v ∈ ran(f) n ∈ ℕ1 i ∈ 1..n k ∈ 1..n f(k) = v i' = k ⊢ i' ∈ 1..n</pre>	<pre>n ∈ ℕ f ∈ 1..n → D v ∈ ran(f) n ∈ ℕ1 i ∈ 1..n k ∈ 1..n f(k) = v ⊢ k ∈ 1..n</pre>
--	---	---

Simplification performed by the PO Generator

```
search ≡
status
ordinary
any
k
where
grd1 : k ∈ 1..n
grd2 : f(k) = v
then
act1 : i := k
end
```

- In what follows, we'll show the **simplified form** only



# Purpose of the Feasibility PO (FIS)

- Ensuring that each **non-deterministic action is feasible**.
- For an event "evt" and a non-deterministic action "act" in it, the name of this PO is:

evt/act/FIS



# Formal Definition of the Feasibility PO (FIS)

<pre>evt any x where G(x, s, c, v) then v :  BAP(x, s, c, v, v') end</pre>	<pre>s : seen sets c : seen constants v : variables A(s, c) : seen axioms I(s, c, v) : invariants evt : specific event x : event parameters G(x, s, c, v) : event guards BAP(x, s, c, v, v') : event action</pre>
<pre>Axioms Invariants Guards of the event ⊢ ∃v' · Before-after predicate</pre>	<pre>evt/act/FIS A(s, c) I(s, c, v) G(x, s, c, v) ⊢ ∃v' · BAP(x, s, c, v, v')</pre>



# Example in Machine **m\_0b (FIS)**

<pre>context ctx_0 sets D constants n f v axioms axm1 : n ∈ ℕ axm2 : f ∈ 1..n → D axm3 : v ∈ ran(f) thm1 : n ∈ ℕ1 end</pre>	<pre>initialisation ≡ status ordinary then act1 : i := 1 end</pre>
<pre>machine m_0b sees ctx_0 variables i invariants inv1 : i ∈ 1..n events ... end</pre>	<pre>search ≡ status ordinary then act1 : i :  i' ∈ 1..n ∧ f(i') = v end</pre>

- Among others, **one feasibility PO** is generated:
- **search/act1/FIS**



<pre>axm1 axm2 axm3 thm1 inv1 grd ┌ ∃i' · before-after predicate</pre>	<pre>n ∈ ℕ f ∈ 1..n → D v ∈ ran(f) n ∈ ℕ1 i ∈ 1..n no guard in event search ┌ ∃i' · i' ∈ 1..n ∧ f(i') = v</pre>
--	---

```
search ≡
status
ordinary
then
act1 : i : | i' ∈ 1..n ∧ f(i') = v
end
```



- Ensuring that the **concrete guards** in the refining event are **stronger** than the **abstract ones**.
- This ensures that when a **concrete event is enabled** then so is the **corresponding abstract one**.
- For a concrete event “**evt**” and an abstract guard “**grd**” in the corresponding abstract event, the name of this PO is:  
evt/grd/GRD



<pre>evt0 any x where g(x, s, c, v) ... then ... end</pre>	<pre>evt refines evt0 any y where H(y, s, c, w) with x : W(x, y, s, c, w) then ... end</pre>	<pre>s : seen sets c : seen constants v : abstract variables w : concrete variables A(s, c) : seen axioms I(s, c, v) : abs. invariants J(s, c, v, w) : conc. invariants. evt : specific concrete event x : abstract event parameter y : concrete event parameter g(x, s, c, v) : abstract event specific guard H(y, s, c, w) : concrete event guards</pre>
--	--	--

<pre>Axioms Abstract invariants Concrete invariants Concrete event guards witness predicate ┌ Abstract event specific guard</pre>	<pre>evt / grd / GRD</pre>	<pre>A(s, c) I(s, c, v) J(s, c, v, w) H(y, s, c, w) W(x, y, s, c, w) ┌ g(x, s, c, v)</pre>
---	----------------------------	--

- It is simplified when there are no parameters



<pre>machine m_1a refines m_0a sees ctx_0 variables i j invariants inv1 : j ∈ 0..n-1 inv2 : v ∉ f[1..j] thm1 : v ∈ f[j+1..n] variant n-j events ... end</pre>	<pre>initialisation ≡ status ordinary then act1 : i := 1 act2 : j := 0 end</pre>	<pre>(abstract-)search ≡ status ordinary refines any k where grd1 : k ∈ 1..n grd2 : f(k) = v then act1 : i := k end</pre>
---	--	---

<pre>search ≡ status ordinary refines search when grd1 : f(j+1) = v with k : j+1 = k then act1 : i := j+1 end</pre>	<pre>progress ≡ status convergent when grd1 : f(j+1) ≠ v then act1 : j := j+1 end</pre>
---	---

- Among others, **two guard strengthening POs** are generated:  
 - search/grd1/GRD  
 - search/grd2/GRD



<pre>axm1 axm2 axm3 thm1 of ctx_0 inv1 (abstract) inv1 (concrete) inv2 (concrete) thm1 of m_1a grd1 (concrete) witness predicate ┌ grd2 (abstract)</pre>	<pre>n ∈ ℕ f ∈ 1..n → D v ∈ ran(f) n ∈ ℕ i ∈ 1..n j ∈ 0..n-1 v ∉ f[1..j] v ∈ f[j+1..n] f(j+1) = v ┌ j+1 = k └ f(k) = v</pre>
--	--

<pre>search ≡ status ordinary refines search when grd1 : f(j+1) = v with k : j+1 = k then act1 : i := j+1 end</pre>	<pre>(abstract-)search ≡ status ordinary any k where grd1 : k ∈ 1..n grd2 : f(k) = v then act1 : i := k end</pre>
---	---



- Ensuring that each **concrete invariant is preserved by each pair of concrete and abstract events.**
- For an event "evt" and a concrete invariant "inv" the name of this PO is:

evt/inv/INV



<pre>evt0 any x where ... then v :  BA1(v, v', ...) end</pre>	<pre>evt refines evt0 any y where H(y, s, c, w) with x : W1(x, y, s, c, w) v' : W2(y, v', s, c, w) then w :  BA2(w, w', ...) end</pre>	<pre>s : seen sets c : seen constants v : abstract vrbis w : concrete vrbis A(s, c) : seen axioms I(s, c, v) : abs. invars. J(s, c, v, w) : conc. invars. H(y, s, c, w) : concrete event x : concrete prm y : abstract prm H(y, s, c, w) : concrete prm W1(x, y, s, c, w) : concrete guards W2(y, v', s, c, w) : abstract action BA2(w, w', ...) : modified specific invariant j(s, c, v', w')</pre>
---	--	--

<pre>Axioms Abstract invariants Concrete invariants Concrete event guards witness predicate witness predicate Concrete before-after predicate ┌ Modified Specific Invariant</pre>	<pre>evt / act / SIM</pre>	<pre>A(s, c) I(s, c, v) J(s, c, v, w) H(y, s, c, w) W1(x, y, s, c, w) W2(y, v', s, c, w) BA2(w, w', ...) ┌ j(s, c, v', w')</pre>
---	----------------------------	--



- In case of the initialization event,  $I(s, c, v)$  and  $J(s, c, v, w)$  is removed from the hypotheses

<pre>machine m_1a refines m_0a sees ctx_0 variables i j invariants inv1 : j ∈ 0..n-1 inv2 : v ∉ f[1..j] thm1 : v ∈ f[j+1..n] variant n-j events ... end</pre>	<pre>initialisation ≡ status ordinary then act1 : i := 1 act2 : j := 0 end</pre>	<pre>(abstract-)search ≡ status ordinary any k where grd1 : k ∈ 1..n grd2 : f(k) = v then act1 : i := k end</pre>
---	--	---

<pre>search ≡ status ordinary refines search when grd1 : f(j+1) = v with k : j+1 = k then act1 : i := j+1 end</pre>	<pre>progress ≡ status convergent when grd1 : f(j+1) ≠ v then act1 : j := j+1 end</pre>
---	---

- Among others, **four invariant preservation POs** are generated:
  - progress/inv1/INV
  - progress/inv2/INV
  - initialization/inv1/INV
  - initialization/inv2/INV



# Proof Obligation **progress/inv1/INV**

<pre> axm1 axm2 axm3 thm1 of ctx_0 inv1 (abstract) inv1 (concrete) inv2 (concrete) thm1 of m_1a grd1 (concrete) ┌ modified specific invariant         </pre>	<pre> n ∈ ℕ f ∈ 1..n → D v ∈ ran(f) n ∈ ℕ1 i ∈ 1..n j ∈ 0..n-1 v ∉ f[1..j] v ∈ f[j+1..n] f(j+1) ≠ v ┌ j+1 ∈ 0..n-1         </pre>
--	---

```

progress ≡
status convergent
when
  grd1 : f(j+1) ≠ v
then
  act1 : j := j+1
end
    
```



# Purpose of the Simulation PO (SIM)

- Ensuring that each **action** in a concrete event **simulates** the corresponding abstract action
- This ensures that when a **concrete event** is “executed” then what it does is **not contradictory** with what the corresponding **abstract event does**.
- For a concrete event “**evt**” and an action “**act**” in abstract event, the name of this PO is:

evt/act/SIM



# Formal Definition of the Simulation PO (SIM)

<pre> evt0 any x where ... then v :  BA1(v, v', ...) end         </pre>	<pre> evt refines evt0 any y where H(y, s, c, w) with x : W1(x, y, s, c, w) v' : W2(y, v', s, c, w) then w :  BA2(w, w', ...) end         </pre>	<pre> s      : seen sets c      : seen constants v      : abstract vrbis w      : concrete vrbis A(s, c) : seen axioms I(s, c, v) : abs. invariants J(s, c, v, w) : conc. invariants evt    : concrete event x      : abstract prm y      : concrete prm H(y, s, c, w) : concrete guards BA1(v, v') : abstract action BA2(w, w') : concrete action         </pre>
<pre> Axioms Abstract invariants Concrete invariants Concrete event guards witness predicate witness predicate Concrete before-after predicate ┌ Abstract before-after predicate         </pre>	<p>evt / act / SIM</p>	<pre> A(s, c) I(s, c, v) J(s, c, v, w) H(y, s, c, w) W1(x, y, s, c, w) W2(y, v', s, c, w) BA2(w, w', ...) ┌ BA1(v, v', ...)         </pre>



# Example in Mch m\_1a Refining Mch m\_0a (SIM)

<pre> machine m_1a refines m_0a sees ctx_0 variables i j invariants inv1 : j ∈ 0..n-1 inv2 : v ∉ f[1..j] thm1 : v ∈ f[j+1..n] variant n-j events ... end         </pre>	<pre> initialisation ≡ status ordinary then act1 : i := 1 act2 : j := 0 end         </pre>	<pre> (abstract-)search ≡ status ordinary any k where grd1 : k ∈ 1..n grd2 : f(k) = v then act1 : i := k end         </pre>
<pre> search ≡ status ordinary refines search when grd1 : f(j+1) = v with k : j+1 = k then act1 : i := j+1 end         </pre>	<pre> progress ≡ status convergent when grd1 : f(j+1) ≠ v then act1 : j := j+1 end         </pre>	

- Among others, **one simulation PO** is generated:  
- search/act1/SIM



```

axm1
axm2
axm3
thm1 of ctx_0
inv1 (abstract)
inv1 (concrete)
inv2 (concrete)
thm1 of m_1a
grd1 (concrete)
witness predicate
┌
before-after predicate (abstract)
    
```

```

n ∈ ℕ
f ∈ 1..n → D
v ∈ ran(f)
n ∈ ℕ
i ∈ 1..n
j ∈ 0..n-1
v ∉ f[1..j]
v ∈ f[j+1..n]
f(j+1) = v
j+1 = k
┌
k = j+1
    
```

```

search ≡
status
ordinary
refines
search
when
grd1 : f(j+1) = v
with
k : j+1 = k
then
act1 : i := j+1
end
    
```

```

(abstract-)search ≡
status
ordinary
any
k
where
grd1 : k ∈ 1..n
grd2 : f(k) = v
then
act1 : i := k
end
    
```



- Ensuring that under the guards of each **convergent event** a proposed numeric variant is indeed a **natural number**
- For a convergent event "evt", the name of this PO is: **evt/NAT**



```

machine
m
refines
...
sees
...
variables
v
invariants
l(s, c, v)
events
...
variant
n(s, c, v)
end
    
```

```

evt
status
convergent
any x where
G(x, s, c, v)
then
A
end
    
```

s : seen sets  
c : seen constants  
v : variables  
A(s, c) : seen axioms  
l(s, c, v) : abs. invts.  
J(s, c, v, w) : conc. invts.  
evt : specific event  
x : event parameters  
G(x, s, c, v) : event guards  
n(s, c, v) : numeric variant

```

Axioms and theorems
Abstract invariants and theorems
Concrete invariants and theorems
Event guards
┌
a numeric variant is a natural number
    
```

evt/NAT

```

A(s, c)
l(s, c, v)
J(s, c, v, w)
G(x, s, c, v)
┌
n(s, c, v) ∈ ℕ
    
```



```

machine
m_1a
refines
m_0a
sees
ctx_0
variables
i
j
invariants
inv1 : j ∈ 0..n-1
inv2 : v ∉ f[1..j]
thm1 : v ∈ f[j+1..n]
variant
n-j
events
...
end
    
```

```

initialisation ≡
status ordinary
then
act1 : i := 1
act2 : j := 0
end
    
```

```

search ≡
status ordinary
refines
search
when
grd1 : f(j+1) = v
with
k : j+1 = k
then
act1 : i := j+1
end
    
```

- Among others, **one numeric variant PO** is generated:  
- **progress/NAT**

```

progress ≡
status convergent
when
grd1 : f(j+1) ≠ v
then
act1 : j := j+1
end
    
```





# Proof Obligation **progress/NAT**

**axm1**  
**axm2**  
**axm3**  
**thm1** of **ctx\_0**  
**inv1** (abstract)  
**inv1** (concrete)  
**inv2** (concrete)  
**thm1** of **m\_1a**  
**grd1** (concrete)  
 $\vdash$  variant is a natural number

$n \in \mathbb{N}$   
 $f \in 1..n \rightarrow D$   
 $v \in \text{ran}(f)$   
 $n \in \mathbb{N1}$   
 $i \in 1..n$   
 $j \in 0..n-1$   
 $v \notin f[1..j]$   
 $v \in f[j+1..n]$   
 $f(j+1) \neq v$   
 $\vdash$   
 $n - j \in \mathbb{N}$

**machine**  
**m\_1a**  
**refines**  
**m\_0a**  
 ...  
**variant**  
 $n - j$   
**events**  
 ...  
**end**

**progress**  $\hat{=}$   
**status** **convergent**  
**when**  
**grd1** :  $f(j+1) \neq v$   
**then**  
**act1** :  $j := j + 1$   
**end**



# Purpose of the Set Variant PO (**FIN**)

- Ensuring that a proposed **set variant** is indeed a **finite** set
- The name of this PO is:

FIN



# Formal Definition of the Set Variant (**FIN**)

**machine**  
**m**  
**refines**  
 ...  
**sees**  
 ...  
**variables**  
 $v$   
**invariants**  
 $J(s, c, v, w)$   
**events**  
 ...  
**variant**  
 $t(s, c, v)$   
**end**

$s$  : seen sets  
 $c$  : seen constants  
 $v$  : variables  
 $A(s, c)$  : seen axioms  
 $I(s, c, v)$  : abs. invts.  
 $J(s, c, v, w)$  : conc. invts.  
 $t(s, c, v)$  : set variant

Axioms  
 Abstract invariants  
 Concrete invariants  
 $\vdash$   
 Finiteness of set variant

FIN

$A(s, c)$   
 $I(s, c, v)$   
 $J(s, c, v, w)$   
 $\vdash$   
 $\text{finite}(t(s, c, v))$



# Example in Mch m\_1b Refining Mch m\_0b (**FIN**)

**machine**  
**m\_1b**  
**refines**  
**m\_0b**  
**sees**  
**ctx\_0**  
**variables**  
 $i$   
 $j$   
**invariants**  
**inv1** :  $j \in 0..n-1$   
**inv2** :  $v \notin f[i..j]$   
**thm1** :  $v \in f[j+1..n]$   
**variant**  
 $j..n$   
**events**  
 ...  
**end**

**initialisation**  $\hat{=}$   
**status** **ordinary**  
**then**  
**act1** :  $i := 1$   
**act2** :  $j := 0$   
**end**

**search**  $\hat{=}$   
**status** **ordinary**  
**refines** **search**  
**when**  
**grd1** :  $f(j+1) = v$   
**then**  
**act1** :  $i := j + 1$   
**end**

**progress**  $\hat{=}$   
**status** **convergent**  
**when**  
**grd1** :  $f(j+1) \neq v$   
**then**  
**act1** :  $j := j + 1$   
**end**

- Among others, **one finiteness PO** is generated





# Proof Obligation **progress**/VAR

axm1  
axm2  
axm3  
thm1 of ctx\_0  
inv1 (abstract)  
inv1 (concrete)  
inv2 (concrete)  
thm1 of m\_1a  
grd1 (concrete)

⊢ variant is a natural number

$n \in \mathbb{N}$   
 $f \in 1..n \rightarrow D$   
 $v \in \text{ran}(f)$   
 $n \in \mathbb{N}1$   
 $i \in 1..n$   
 $j \in 0..n-1$   
 $v \notin f[1..j]$   
 $v \in f[j+1..n]$   
 $f(j+1) = v$

⊢  $n - (j+1) < n - j$

machine  
m\_1a  
refines  
m\_0a  
...  
variant  
 $n - j$   
events  
...  
end

progress  $\hat{=}$   
status  
convergent  
when  
grd1 :  $f(j+1) \neq v$   
then  
act1 :  $j := j+1$   
end

# Purpose of the Set Variant Decreasing PO (VAR)

- Ensuring that each **convergent event** decreases the proposed set variant
- For a convergent event "evt", the name of this PO is:  
evt/VAR



# Formal Def. of the Set Variant Decreasing PO (VAR)

evt  
status  
convergent  
any x where  
 $G(x, s, c, w)$   
then  
 $v : | BAP(x, s, c, w, w')$   
end

s : seen sets  
c : seen constants  
v : variables  
 $A(s, c)$  : seen axioms  
 $I(s, c, v)$  : abs. invariants  
 $J(s, c, v, w)$  : conc. invariants  
evt : specific event  
x : event parameters  
 $G(x, s, c, v)$  : event guards  
 $BAP(x, s, c, w, w')$  : event before-after predicate  
 $t(s, c, w)$  : set variant

Axioms and theorems  
Abstract invariants and theorems  
Concrete invariants and theorems  
Guards of the event  
Before-after predicate of the event

evt/VAR

$A(s, c)$   
 $I(s, c, v)$   
 $J(s, c, v, w)$   
 $G(x, s, c, v)$   
 $BAP(x, s, c, w, w')$   
⊢  $t(s, c, w') \subset t(s, c, w)$

⊢ Modified variant strictly included in variant

# Example in Mch m\_1b Refining Mch m\_0b (VAR)

machine  
m\_1b  
refines  
m\_0b  
sees  
ctx\_0  
variables  
i  
j  
invariants  
inv1 :  $j \in 0..n-1$   
inv2 :  $v \notin f[1..j]$   
thm1 :  $v \in f[j+1..n]$   
variant  
 $j..n$   
events  
...  
end

initialisation  $\hat{=}$   
status ordinary  
then  
act1 :  $j := 1$   
act2 :  $j := 0$   
end

search  $\hat{=}$   
status ordinary  
refines search  
when  
grd1 :  $f(j+1) = v$   
then  
act1 :  $i := j+1$   
end

progress  $\hat{=}$   
status convergent  
when  
grd1 :  $f(j+1) \neq v$   
then  
act1 :  $j := j+1$   
end

- Among others, **one variant decreasing PO** is generated:

- **progress/VAR**



<pre>axm1 axm2 axm3 thm1 of ctx_0 inv1 (abstract) inv1 (concrete) inv2 (concrete) thm1 of m_1a inv2 (concrete) grd1 (concrete) ┌ variant is a natural number</pre>	<pre>n ∈ ℕ f ∈ 1 .. n → D v ∈ ran(f) n ∈ ℕ1 i ∈ 1 .. n j ∈ 0 .. n - 1 v ∉ f[1 .. j] v ∈ f[j + 1 .. n] f(j + 1) = v ┌ j + 1 .. n ⊂ j .. n</pre>
--	--

<pre>machine m_1b refines m_0b ... variant j .. n events ... end</pre>	<pre>progress ≡ status convergent when grd1 : f(j + 1) ≠ v then act1 : j := j + 1 end</pre>
--	---



- Ensuring that each **witness** proposed in the witness predicate of a concrete event indeed **exists**
- For a concrete event "evt", and an abstract parameter **x** the name of this PO is:

evt/x/WFIS



## Formal Definition of the Witness Feasibility PO (WFIS)

<pre>evt refines evt0 any y where H(y, s, c, w) with x : W(x, y, s, c, w) then ... end</pre>	<pre>s : seen sets c : seen constants v : abstract variables w : concrete variables A(s, c) : seen axioms I(s, c, v) : abs. invariants J(s, c, v, w) : conc. invariants evt : specific concrete event x : abstract event parameter y : concrete event parameter H(y, s, c, w) : concrete event guards W(x, y, s, c, w) : witness predicate</pre>
--	--

<pre>Axioms Abstract invariants Concrete invariants Concrete event guards ┌ ∃x · Witness</pre>	<pre>evt/x/WFIS</pre>
--	-----------------------

```
A(s, c)
I(s, c, v)
J(s, c, v, w)
H(y, s, c, w)
┌
∃x · W(x, y, s, c, w)
```



## Example in Mch m\_1a Refining Mch m\_0a (WFIS)

```
machine
m_1a
refines
m_0a
sees
ctx_0
variables
i
j
invariants
inv1 : j ∈ 0 .. n - 1
inv2 : v ∉ f[1 .. j]
thm1 : v ∈ f[j + 1 .. n]
variant
n - j
events
...
end
```

```
initialisation ≡
status ordinary
then
act1 : i := 1
act2 : j := 0
end
```

```
search ≡
status ordinary
refines search
when
grd1 : f(j + 1) = v
with
k : j + 1 = k
then
act1 : i := j + 1
end
```

```
progress ≡
status convergent
when
grd1 : f(j + 1) ≠ v
then
act1 : j := j + 1
end
```

- Among others, **one witness feasibility PO** is generated:  
- search/k/WFIS



<b>axm1</b> <b>axm2</b> <b>axm3</b> <b>thm1</b> of <b>ctx_0</b> <b>inv1</b> (abstract) <b>inv1</b> (concrete) <b>inv2</b> (concrete) <b>thm1</b> of <b>m_1a</b> <b>grd1</b> (concrete) $\vdash$ $\exists k \cdot \text{variant predicate}$	$n \in \mathbb{N}$ $f \in 1..n \rightarrow D$ $v \in \text{ran}(f)$ $n \in \mathbb{N}1$ $i \in 1..n$ $j \in 0..n-1$ $v \notin f[1..j]$ $v \in f[j+1..n]$ $f(j+1) = v$ $\vdash$ $\exists k \cdot j+1 = k$
--	--

```

search  $\hat{=}$ 
  status ordinary
  refines search
  when
    grd1 :  $f(j+1) = v$ 
  with
     $k : j+1 = k$ 
  then
    act1 :  $i := j+1$ 
  end
    
```



- Ensuring that a proposed **context theorem** is indeed **provable**
- Theorems are **important** in that they might **simplify some proofs**
- For a theorem "**thm**" in a context, the name of this PO is:  

thm/THM



```

context
  ctx
  extends
  ...
  sets
  s
  constants
  c
  axioms
  A(s, c)
  ...
  thm : P(s, c)
  ...
  end
    
```

$s$  : seen sets  
 $c$  : seen constants  
 $A(s, c)$  : seen axioms and previous theorems  
 $P(s, c)$  : specific theorem

Axioms	
$\vdash$	<b>thm/THM</b>
Theorem	

$\vdash$   
 $A(s, c)$   
 $P(s, c)$



```

context
  ctx_0
  sets
  D
  constants
  n
  f
  v
  axioms
  axm1 :  $n \in \mathbb{N}$ 
  axm2 :  $f \in 1..n \rightarrow D$ 
  axm3 :  $v \in \text{ran}(f)$ 
  thm1 :  $n \in \mathbb{N}1$ 
  end
    
```

- **One theorem PO** is generated: **thm1/THM**



# Proof Obligation **thm1/THM**

axm1 axm2 axm3 $\vdash$ <b>thm1</b>	$\frac{n \in \mathbb{N} \quad f \in 1..n \rightarrow D \quad v \in \text{ran}(f)}{\vdash n \in \mathbb{N}1}$
---	--



# Purpose of a Machine Theorem PO (**THM**)

- Ensuring that a proposed **machine theorem** is indeed **provable**
- Theorems are **important** in that they might **simplify some proofs**
- For a theorem "**thm**" in a machine, the name of this PO is:  
thm/THM



# Formal Definition of the Machine Theorem PO (**THM**)

<pre> machine   m0   refines   ...   sees   ...   variables   v   invariants   I(s, c, v)   ...   thm : P(s, c, v)   ...   events   ... end                 </pre>	<p>s : seen sets                  c : seen constants                  v : variables                  A(s, c) : seen axioms                  I(s, c, v) : invariants and previous thms.                  P(s, c, v) : specific theorem</p>
--	---

Axioms Invariants $\vdash$ Theorem	thm/THM	$\frac{A(s, c) \quad I(s, c, v)}{\vdash P(s, c, v)}$
---	---------	--



# Example in Mch m\_1a Refining Mch m\_0a (**THM**)

```

machine
  m_1a
  refines
  m_0a
  sees
  ctx_0
  variables
  i
  j
  invariants
  inv1 : j ∈ 0..n-1
  inv2 : v ∉ f[1..j]
  thm1 : v ∈ f[j+1..n]
  variant
  n-j
  events
  ...
end
                
```

- Among others, **one theorem PO** is generated: **thm1/THM**



<p><b>axm1</b>  <b>axm2</b>  <b>axm3</b>  <b>thm1</b> of <b>ctx_0</b>  <b>inv1</b> (abstract)  <b>inv1</b> (concrete)  <b>inv2</b> (concrete)  <math>\vdash</math>  <b>thm1</b> of <b>m_1a</b></p>	<p><math>n \in \mathbb{N}</math>  <math>f \in 1..n \rightarrow D</math>  <math>v \in \text{ran}(f)</math>  <math>n \in \mathbb{N}1</math>  <math>i \in 1..n</math>  <math>j \in 0..n-1</math>  <math>v \notin f[1..j]</math>  <math>\vdash</math>  <math>v \in f[j+1..n]</math></p>
--	---



- Ensuring that a **potentially ill-defined** axiom, theorem, invariant, guard, action, variant, or witness is indeed **well-defined**
- For a given modeling element (axm, thm, inv, grd, act), or a variant, or a witness  $x$  in an event  $\text{evt}$ , the names are:  
 axm/WD, thm/WD, inv/WD, grd/WD, act/WD, VWD, evt/ $x$ /WWD



- It depends on the **potentially ill-defined expression**

$\text{inter}(S)$	$S \neq \emptyset$
$\bigcap x \cdot x \in S \wedge P(x) \mid T(x)$	$\exists x \cdot x \in S \wedge P(x)$
$f(E)$	$f$ is a partial function $E \in \text{dom}(f)$
$E/F$	$F \neq 0$
$E \text{ mod } F$	$F \neq 0$
$\text{card}(S)$	$\text{finite}(S)$
$\text{min}(S)$	$S \subseteq \mathbb{Z}$ $\exists x \cdot x \in \mathbb{Z} \wedge (\forall n \cdot n \in S \Rightarrow x \leq n)$
$\text{max}(S)$	$S \subseteq \mathbb{Z}$ $\exists x \cdot x \in \mathbb{Z} \wedge (\forall n \cdot n \in S \Rightarrow x \geq n)$



```

context
  ctx_0
sets  $D$ 
constants  $n, f, v$ 
axioms
  axm1 :  $n \in \mathbb{N}$ 
  axm2 :  $f \in 1..n \rightarrow D$ 
  axm3 :  $v \in \text{ran}(f)$ 
  thm1 :  $n \in \mathbb{N}1$ 
end
    
```

```

initialisation  $\hat{=}$ 
  status
  ordinary
  then
    act1 :  $i := 1$ 
  end
    
```

```

machine
  m_0a
sees ctx_0
variables
   $i$ 
invariants
  inv1 :  $i \in 1..n$ 
events
  ...
end
    
```

```

search  $\hat{=}$ 
  status
  ordinary
  any
   $k$ 
  where
    grd1 :  $k \in 1..n$ 
    grd2 :  $f(k) = v$ 
  then
    act1 :  $i := k$ 
  end
    
```

- One well-definedness PO is generated:  
 - **search/grd2**/WD



<p>axm1 axm2 axm3 thm1 inv1 grd1</p> <p>⊢ WD conditions for <b>grd2</b></p>	<p><math>n \in \mathbb{N}</math> <math>f \in 1..n \rightarrow D</math> <math>v \in \text{ran}(f)</math> <math>n \in \mathbb{N}1</math> <math>i \in 1..n</math> <math>k \in 1..n</math></p> <p>⊢ <math>k \in \text{dom}(f) \wedge f \in \mathbb{Z} \leftrightarrow D</math></p>
---	--



## Summary of all POs of the Examples (1)

- **Context `ctx_0`**
  - `thm1/THM`
- **Machine `m_0a`**
  - `initialisation/inv1/INV`
  - `search/gdr2/WD`
  - `search/inv1/INV`
- **Machine `m_0b`**
  - `initialisation/inv1/INV`
  - `search/inv1/INV`
  - `search/act1/WD`
  - `search/act1/FIS`



<p>evt01 <b>any</b> x <b>where</b> G1(x, s, c, v) <b>then</b> A <b>end</b></p>	<p>evt02 <b>any</b> x <b>where</b> G2(x, s, c, v) <b>then</b> A <b>end</b></p>
<p>evt <b>refines</b> evt01 evt02 <b>any</b> x <b>where</b> H(x, s, c, v) <b>then</b> A <b>end</b></p>	



Axioms and theorems  
Abstract invariants and theorems

## Summary of all POs of the Examples (2)

- **Machine `m_1a`**
  - `thm1/THM`
  - `initialisation/inv1/INV`
  - `initialisation/inv2/INV`
  - `search/gdr1/WD`
  - `search/k/WFIS`
  - `search/gdr1/GRD`
  - `search/gdr2/GRD`
  - `search/act1/SIM`
  - `progress/gdr1/WD`
  - `progress/inv1/INV`
  - `progress/inv2/INV`
  - `progress/VAR`
  - `progress/NAT`





## Summary of all POs of the Examples (3)

- **Machine m\_1b**
  - **thm1/THM**
  - **FIN**
  - **initialisation/inv1/INV**
  - **initialisation/inv2/INV**
  - **search/gdr1/WD**
  - **search/act1/SIM**
  - **progress/gdr1/WD**
  - **progress/inv1/INV**
  - **progress/inv2/INV**
  - **progress/VAR**

